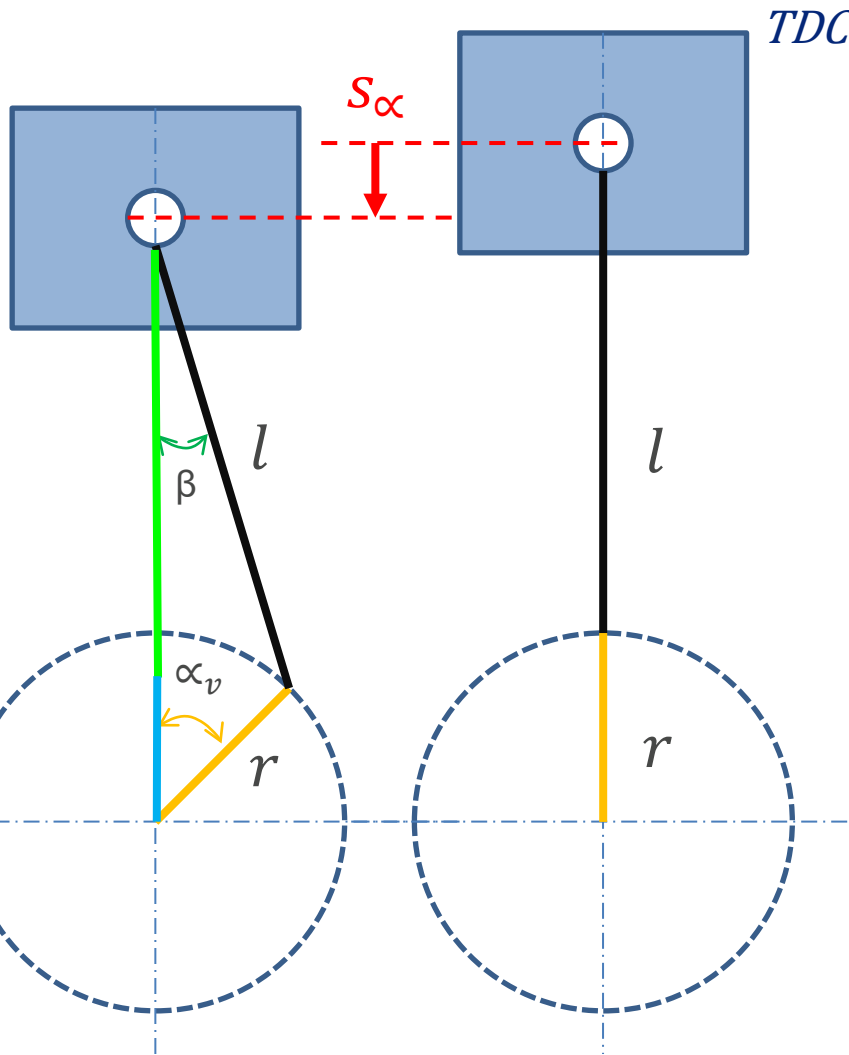

Engine Kinematics

AUTOPISTA

Pistón's position for "alpha"



$$s_{\alpha} = r + l - l * \cos\beta - r * \cos\alpha$$

Applying trigonometry

$$r * \sin\alpha = l * \sin\beta$$

Clearing sinus

$$\sin\beta = \frac{r}{l} \sin\alpha = \lambda_s * \sin\alpha$$

Applying sin/cos law

$$\sin^2\beta + \cos^2\beta = 1$$

$$\cos\beta = \sqrt{1 - \sin^2\beta}$$

$$\cos\beta = \sqrt{1 - \lambda_s^2 \sin^2\alpha}$$

TDC = Top Dead Center

Pistón's position for "alpha"

$$s_{\alpha} = r + l - l * \cos\beta - r * \cos \alpha \quad \cos\beta = \sqrt{1 - \lambda_s^2 \sin^2 \alpha} \quad \lambda_s = \frac{r}{l}$$

- Replacing

$$s_{\alpha} = r + l - l * \sqrt{1 - \lambda_s^2 \sin^2 \alpha} - r * \cos \alpha$$

*Piston's position
equation for an angle
Alpha.*

- Applying Taylor's expansion and sin/cos identity of double angle

$$s_{\alpha} \sim r \left[(1 - \cos \alpha) + \frac{\lambda_s}{4} * (1 - \cos 2 \alpha) \right]$$

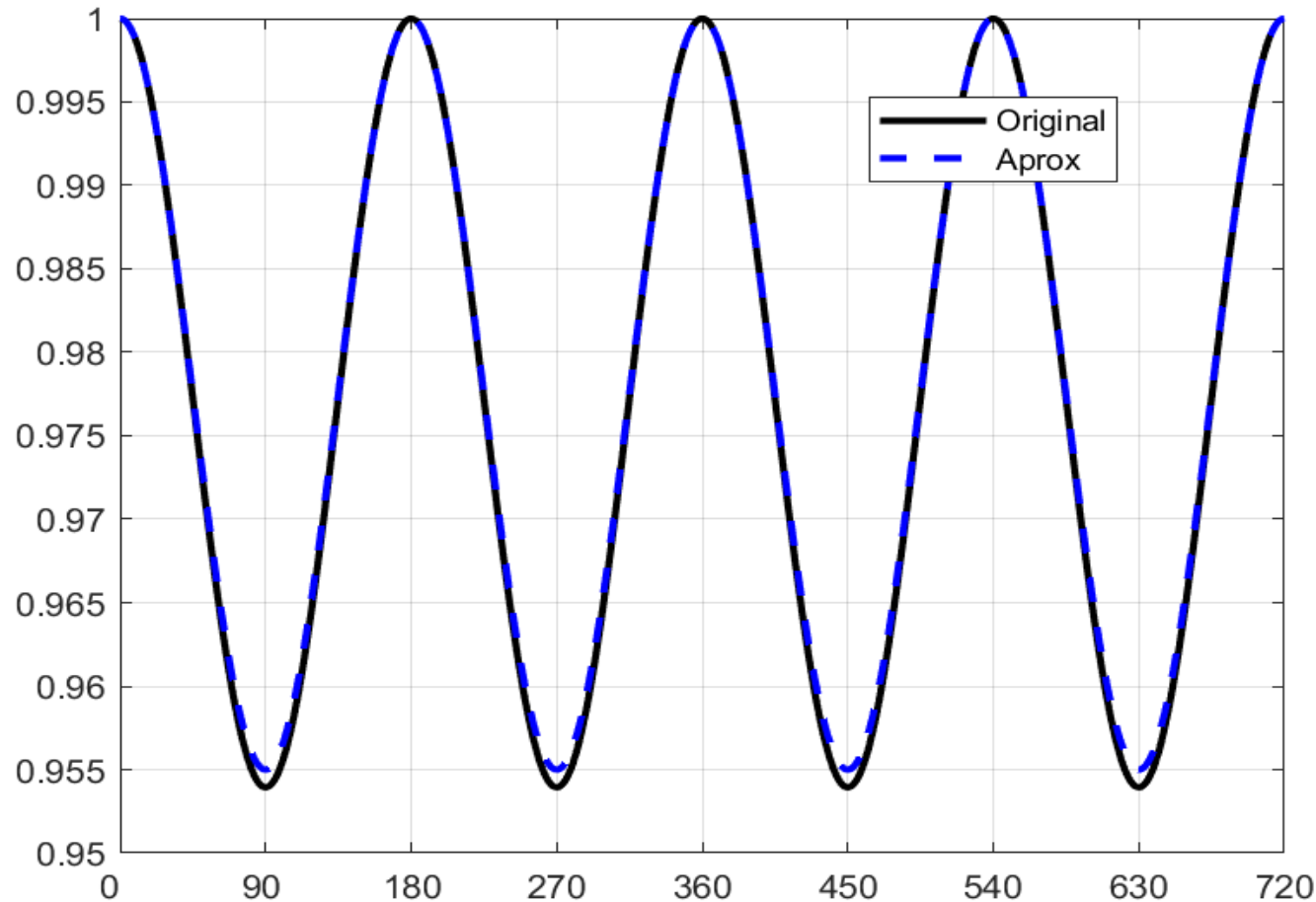
$$\sqrt{1 - \lambda_s^2 \sin^2 \alpha} \sim 1 - \frac{1}{2} * \lambda_s^2 \sin^2 \alpha$$

$$\sin^2 \alpha = \frac{1}{2} * (1 - \cos 2 \alpha)$$

Taylor's expansion



We prove that: $\sqrt{1 - \lambda_s^2 \sin^2 \alpha} \sim 1 - \frac{1}{2} * \lambda_s^2 \sin^2 \alpha$



Velocity and Acceleration

$$s_\alpha \sim r \left[(1 - \cos \alpha) + \frac{\lambda_s}{4} * (1 - \cos 2 \alpha) \right]$$

- Derivative of the position -> Velocity

$$\dot{s}_\alpha = \frac{ds_\alpha}{d\alpha} \cdot \frac{d\alpha}{dt} = \frac{ds_\alpha}{d\alpha} * \omega \quad \omega = \text{angular speed} = 2 * \pi * n \text{ [rad/s]}$$

$$\dot{s}_\alpha \sim r * \omega \left(\sin \alpha + \frac{\lambda_s}{2} * \sin 2 \alpha \right)$$

- Derivative of the velocity -> Acceleration

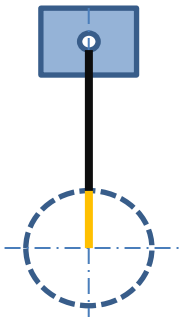
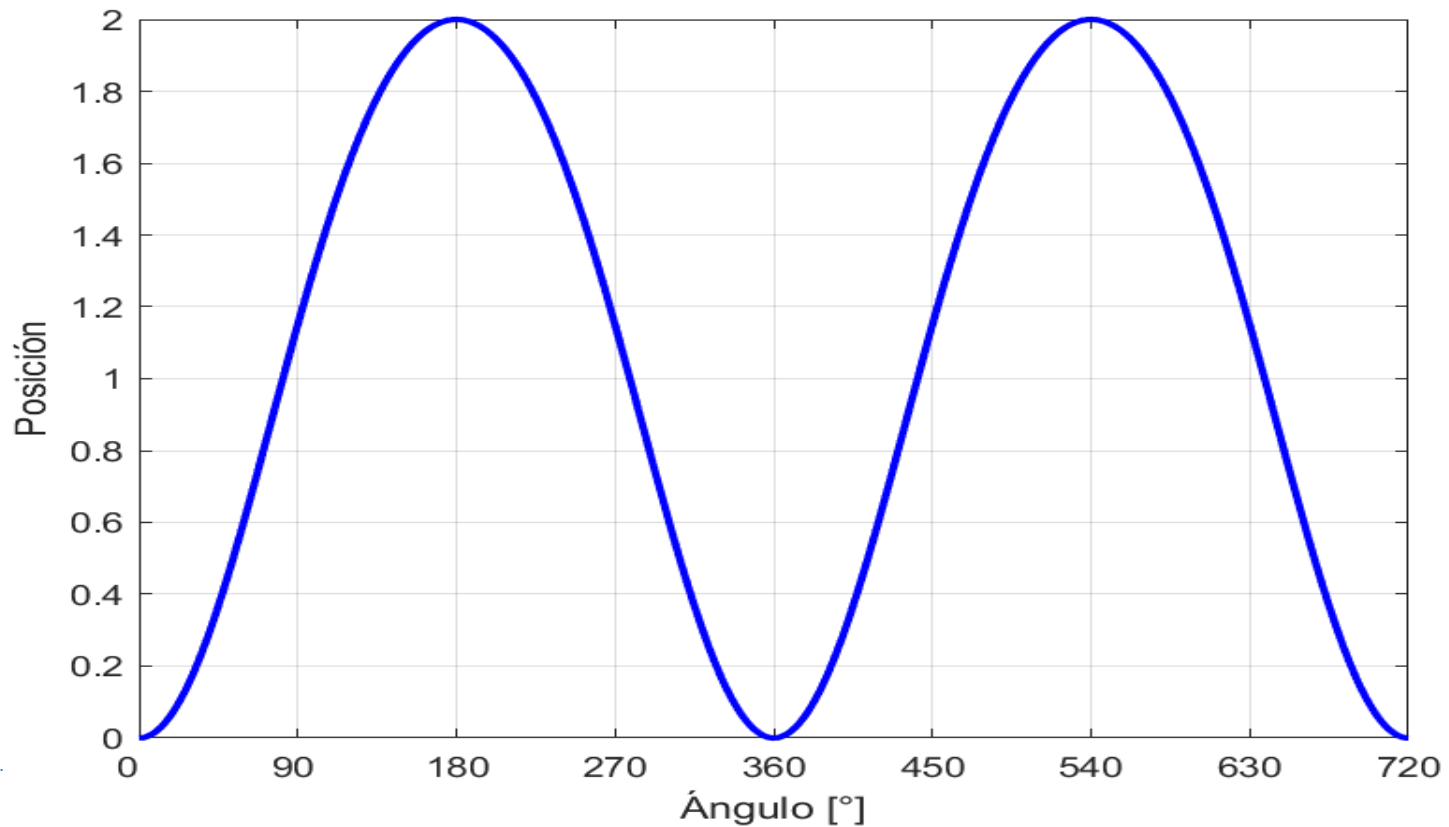
$$\ddot{s}_\alpha = \frac{d^2 s_\alpha}{d\alpha^2} \cdot \frac{d^2 \alpha}{dt^2} = \frac{d^2 s_\alpha}{d\alpha^2} * \omega^2$$

$$\ddot{s}_\alpha \sim r * \omega^2 (\cos \alpha + \lambda_s * \cos 2 \alpha)$$

Position

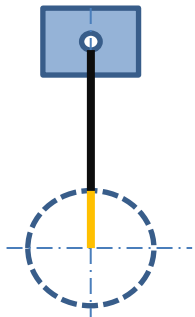
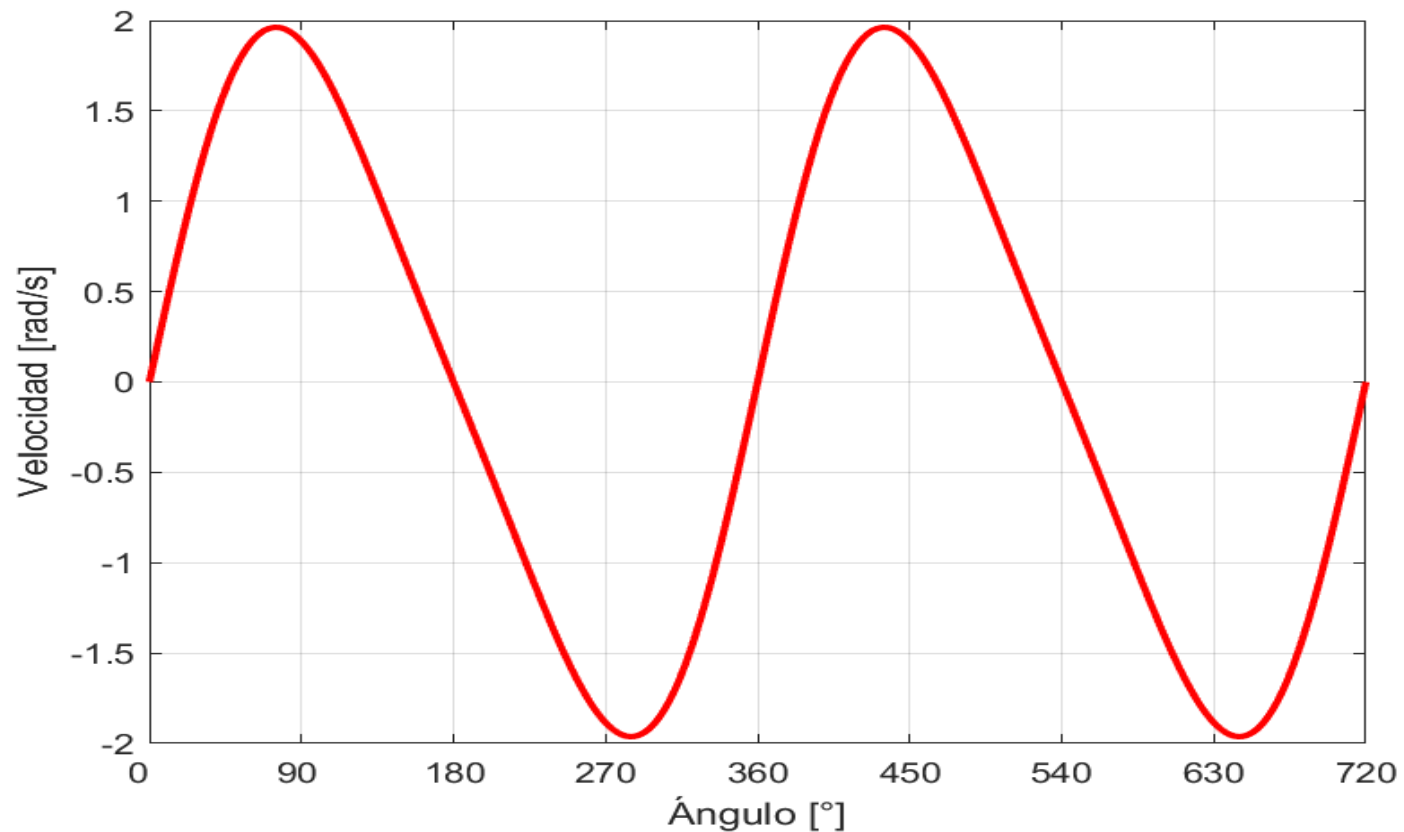
Drawing a graph of the piston's position against "alpha"

$$s_{\alpha} \sim r \left[(1 - \cos \alpha) + \frac{\lambda_s}{4} * (1 - \cos 2 \alpha) \right]$$



Graph of the speed versus “alpha”

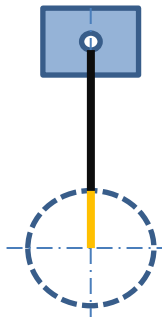
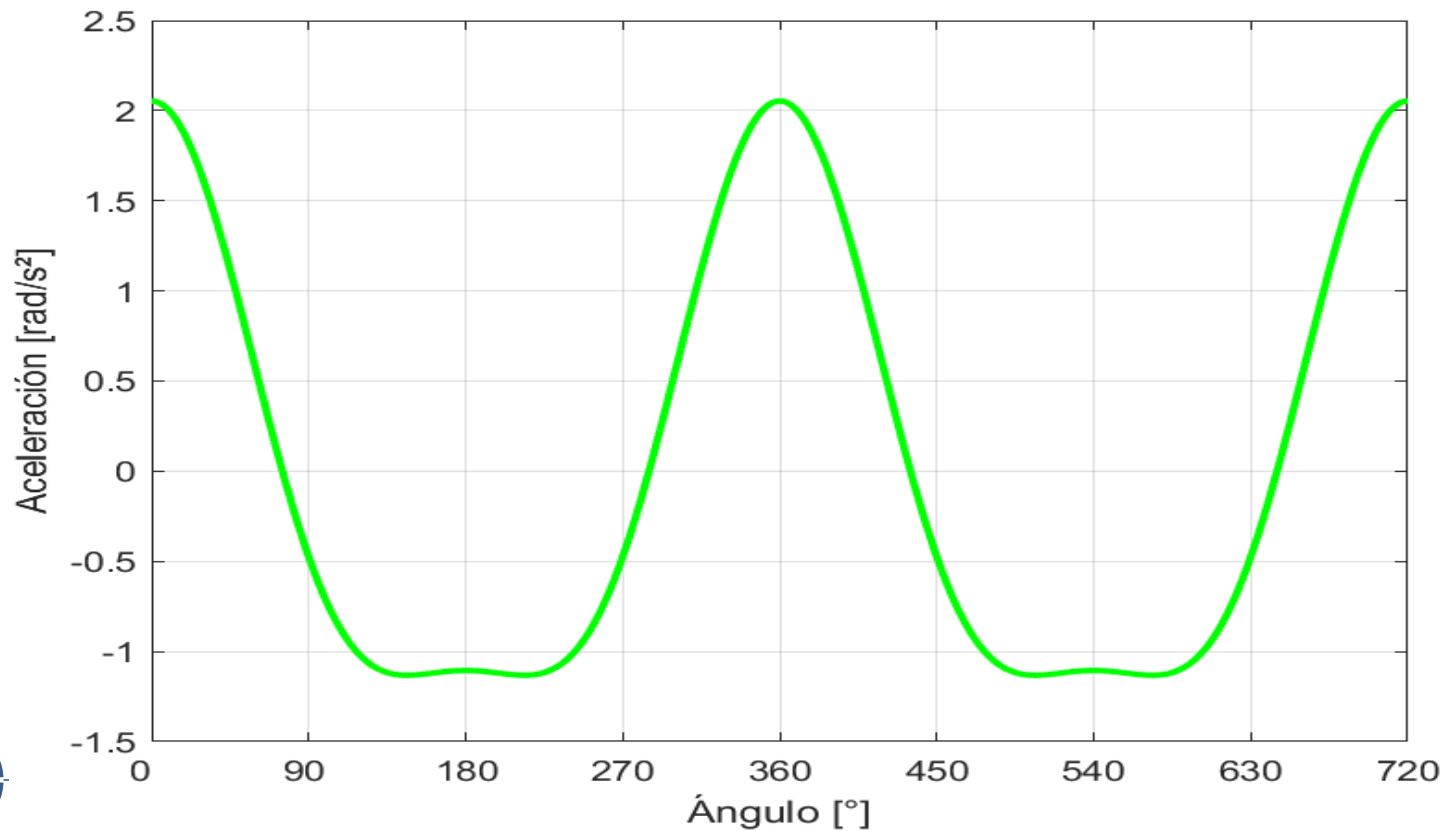
$$\dot{s}_\alpha \sim r * \omega \left(\sin \alpha + \frac{\lambda_s}{2} * \sin 2 \alpha \right)$$



Acceleration

Acceleration's graph versus "alpha"

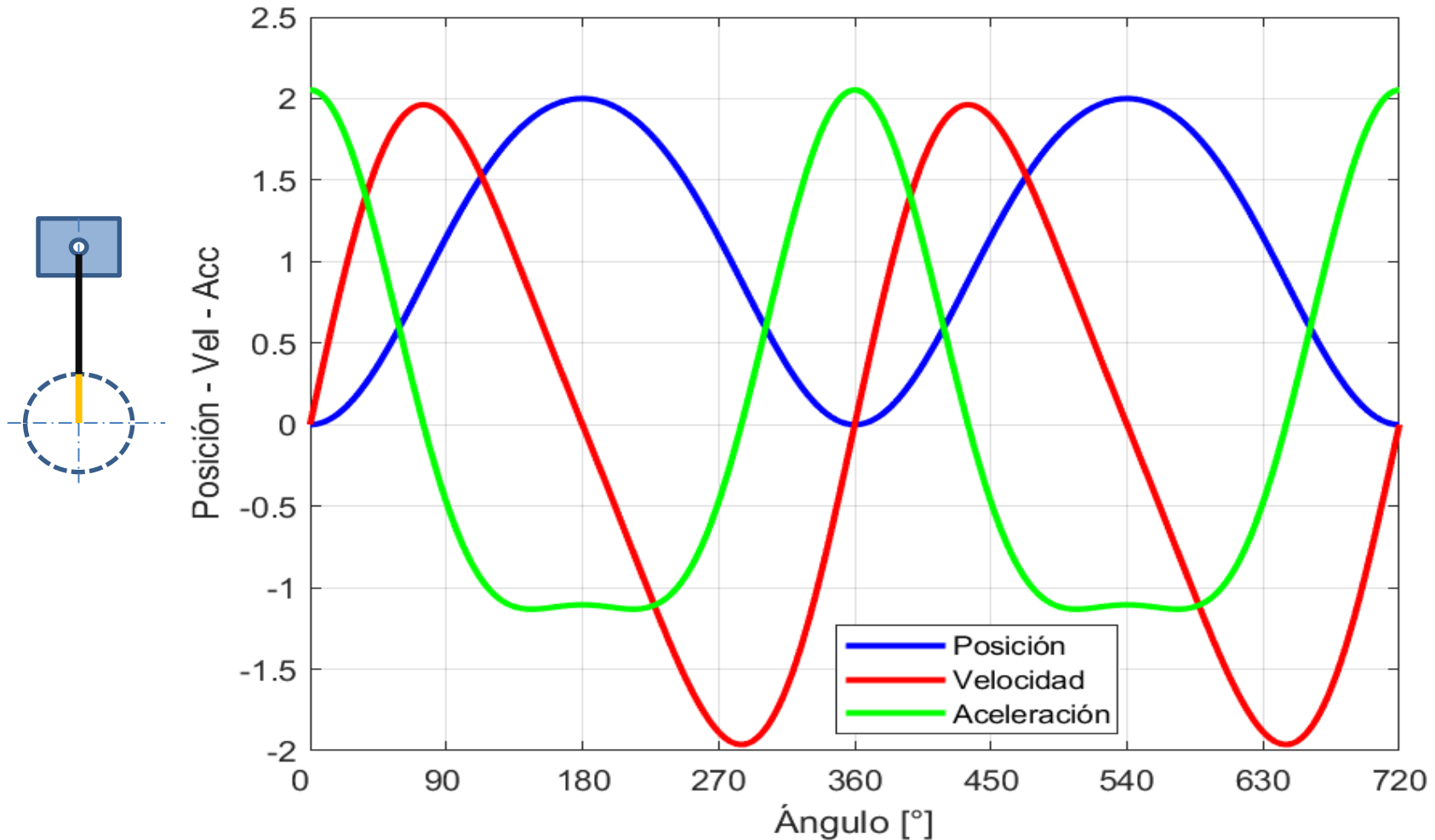
$$\ddot{s}_\alpha \sim r * \omega^2 (\cos \alpha + \lambda_s * \cos 2 \alpha)$$



Position – Velocity – Acceleration



Graphing all together versus “Alpha”



Summary



- Geometry and definition of the angle “alpha”.
- Equations for position, speed and acceleration.
- Taylor’s expansion review.
- With the acceleration’s equation, one can calculate:
 - Mass force ($F_m = \text{mass} * \text{acceleration}$) and
 - Partial Torque of the crankshaft -> The gas forces are not yet considered

Fg.

